

Remarks

This Preliminary Amendment cancels, without prejudice, claims 1-7 in the underlying PCT Application No. PCT/EP2004/052177 and adds new claims 8-14. The new claims, inter alia, conform the claims to United States Patent and Trademark Office rules and do not add any new matter to the application.

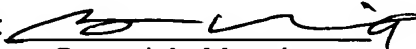
In accordance with 37 C.F.R. § 1.125(b), the Substitute Specification (including Abstract) contains no new matter. The amendments reflected in the Substitute Specification (including Abstract) are to conform the Specification and Abstract to United States Patent and Trademark Office rules or to correct informalities. As required by 37 C.F.R. §§ 1.121(b)(3)(ii) and 1.125(c), a Marked-Up Version of the Substitute Specification comparing the Specification of record and the Substitute Specification also accompanies this Preliminary Amendment. Approval and entry of the Substitute Specification (including Abstract) are respectfully requested.

The underlying PCT Application No. PCT/EP2004/052177 includes an International Search Report, dated December 16, 2004, a copy of which is included. The Search Report includes a list of documents that were considered by the Examiner in the underlying PCT application.

Applicant asserts that the subject matter of the present application is new, non-obvious, and useful. Prompt consideration and allowance of the application are respectfully requested.

Respectfully Submitted,
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LANE ASSIST SYSTEM FOR A MOTOR VEHICLE AND OPERATING METHOD

Background InformationField Of The Invention

The present invention relates to a lane assist system for a motor vehicle including a surround sensor device, which is mounted on the motor vehicle, for detecting the vehicle's lane and a warning device for alerting the driver in the event of the vehicle threatening to depart the lane. The present invention also relates to a method for operating such a lane assist system.

Background Information

In a lane assist system of the above-mentioned type, the lane ahead or beneath the vehicle is detected by a surround sensor. If the vehicle threatens to depart the lane to the right or the left, an acoustic, a visual and/or a haptic warning is output to the driver.

Another possible application of a lane assist system of the above-mentioned type arises when driving on a multi-lane roadway when the driver intends to depart the right lane and change over to the middle lane or the left lane in order to pass a slower moving vehicle traveling ahead. If, at the beginning of the steering process, the surround sensor detects a vehicle rapidly approaching from the rear, the driver is prompted by an acoustic, visual and/or haptic warning to abort the lane change operation.

The lane assist system typically has a sensor system which is made up of a two-dimensional sensor array or only one or a few sensor row(s). As a rule, the sensor system is mounted on the vehicle's front, pointing ahead, and scans a certain roadway section in the vehicle's surroundings. The obtained image information is analogously or digitally processed using known technologies in order to extract information about the roadway markings and the roadway edge. In the event of the vehicle threatening to depart the current lane under danger, the warning device outputs an acoustic, visual and/or haptic alert.

An acoustic alert, for example, may be output in the form of a sound, known as a spike strip rattling sound, specifically on the vehicle side on which the vehicle

threatens to depart the lane. Such a spike strip rattling sound acoustically simulates the crossing of a roadway marking provided with spikes or a profile. As a response to this sound, the driver may for the most part intuitively very quickly carry out a suitable steering correction. However, such an acoustic alert has the disadvantage
 5 that the other vehicle passengers are often intensely disturbed and unsettled.

In the case of a haptic alert, e.g., vibration of the steering wheel, the disturbance of the other vehicle passengers is avoided, but such a vibration alert is not direction-specific, so that the driver is not able to carry out an intuitive targeted steering
 10 correction. Rather, the driver, alarmed by the alert, must initially visually comprehend the instantaneous situation and then initiate an appropriate response. As a result, valuable split seconds are often lost, particularly in critical traffic situations.

Advantages of the Summary Of The Invention

15 The warning device is characteristically designed and set up in such a way that it provides the driver with a haptic indication of direction, i.e., information about the direction in which there is the risk of the perilous lane departure. In this manner, disturbance of the other vehicle passengers due to acoustic signals may be avoided while preserving the direction information in the warning signal. The driver may thus,
 20 in any event after a short adaptation phase, intuitively counter-steer to the perilous lane change.

It is advantageous that the warning device has a vibration device, which cooperates with the driver seat, for generating haptic feedback for the driver by vibrating the
 25 driver seat, the vibration device being designed in such a way that vibrations may be generated on at least two sides of the seat surface, independently of one another.

A secondary warning device for outputting a visual and/or an acoustic warning signal is advantageously provided in addition to the vibration device. Therefore, another
 30 different warning signal may be output in the event that the haptic alert is ignored or remains ineffective. Disturbances of the passengers are thus reduced to a degree unavoidable for the safety of the vehicle passengers.

The vibration device, which cooperates with the driver seat, may advantageously be made up of two vibration elements which are mounted on the left side and the right side of the seat and which may be activated separately and are permanently integrated into the seat. In another embodiment, a vibration mat is provided which is modified in such a way that the vibration elements right and left are able to be separately activated.

The motor vehicle's surround sensor device may advantageously have a sensor, which cooperates with the warning device, for detecting vehicles approaching from the rear and for outputting an alert if, during a change to a new lane, a vehicle rapidly approaches from the rear on the new lane.

The motor vehicle's surround sensor device appropriately contains a radar sensor, an ultrasound sensor, or an image recording camera in particular.

According to the present invention, in a method for operating such a lane assist system, the vehicle's lane is detected, it is judged whether the vehicle threatens to depart the lane under danger, and a warning signal is generated for the driver when the vehicle threatens to depart the lane under danger, the warning signal characteristically providing the driver with acoustic or haptic feedback which contains information about the direction in which there is the risk of the perilous lane departure.

~~Additional advantages arise from the description of exemplary embodiments and from the dependent claims.~~

Drawing

~~The present invention is subsequently explained in greater detail based on the exemplary embodiments illustrated in the drawing.~~

Brief Description Of The Drawings

~~Fig. 1~~ Figure 1 shows a schematic representation of a motor vehicle on a two-lane roadway having a lane assist system according to an exemplary embodiment of the present invention, and

Fig: 2-Figure 2 shows a schematic representation of a lane assist system according to another exemplary embodiment of the present invention in which vibrations of the driver seat indicate the direction of a perilous lane departure.

5 Detailed Description of Exemplary Embodiments

Figure 1 shows a lane assist system according to an exemplary embodiment of the present invention including a schematic representation of a motor vehicle 10 on a two-lane roadway 20, 22. The lane assist system includes a surround sensor device 31 (Figure 2) which, in the exemplary embodiment, contains a forward pointing front
10 sensor 12, which is mounted on the vehicle's front section, and a backward pointing rear sensor 16 which is mounted on the vehicle's rear section.

Visual field 14 of front sensor 12 detects right roadway edge 24 of right lane 20 and roadway marking 26 which divides lanes 20 and 22. A computing unit of the lane
15 assist system, a micro processor for example, determines the position of vehicle 10 relative to lane 20 from the collected sensor data.

Visual field 18 of rear sensor 16 covers the rear area of vehicle 10 in order to detect vehicles 29 approaching from the rear.

20 If vehicle 10 threatens to cross roadway edge 24 and to depart lane 20 to the right, for instance due to a distraction or the overfatigue of the driver, the driver is alerted by the below-described warning and enabled to initiate counter measures. In an embodiment, the latter could also be an automatic intervention in the vehicle's
25 steering system. The warning is implemented by the fact that a warning signal is generated and a vibration unit, which receives the warning signals, generates control signals true to side for the respective element(s) in the driver seat. This prompts the driver to steer again to the right~~left~~ and to abort the lane change operation. An acoustic and/or visual warning signal may additionally also be output here.

30 An acoustic warning signal may also be output when the driver does not respond to the haptic warning and a lane departure continues to be a threat or actually takes place. Due to the fact that, in the exemplary embodiment, the acoustic warning is only output when the haptic warning is not registered or other certain conditions are

mat (e.g., hands not on the steering wheel, or similar), disturbances of the passengers are reduced to a degree unavoidable for the safety of the vehicle passengers.

5 Due to rear sensor 16, which may be omitted in an advantageous embodiment, lane assist system 30 may also be used as an auxiliary device for lane changes, if, for instance, the driver of vehicle 10 intends to depart right lane 20 and change to left lane 22 in order to pass a slower moving vehicle 28 traveling ahead. If, at the beginning of the steering operation, rear sensor 16 detects a vehicle 29 rapidly
10 approaching from behind on lane 22, warning signals are output to the vibration device which subsequently generates control signals true to side for the respective element(s) in the driver seat. This prompts the driver to steer again to the right and to abort the lane change operation. An acoustic warning signal may additionally be output here.

15 This approach is illustrated in Figure 2. Surround sensor device 31 or a processing unit, which analyzes the signals of this sensor device, determines whether and on which vehicle side a lane departure is threatened. An appropriate signal is generated and output to a warning unit 42 which may be part of the processing unit. Vibration
20 elements 44 and 45, which are able to be activated separately from warning unit 42, are installed in the driver seat. As a function of the supplied signal, warning unit 42 activates the right vibration element (in the event of a lane departure to the right) or the left vibration element (in the event of lane departure to the left) which generates a vibrating motion, thereby prompting the driver true to side to execute the required
25 steering correction. The vibration elements are integrated into the seat and situated in such a way that a noticeable vibration is created on part of the seating surface (on the left part in the case of the left vibration element and on the right part in the case of the right vibration element). In another embodiment, a vibration mat is used in the driver seat underneath the seating surface which is designed in such a way that its
30 left and right side are able to be activated separately.

While the present invention is shown and described in particular with regard to preferred exemplary embodiments, it shall be understood by those skilled in the art that design and detail modifications may be made without deviating from the idea

and the scope of the present invention. In a simpler and more cost-effective embodiment, surround sensor device 31 may contain only one sensor 12, for example.

Abstract Of The Disclosure

In order to provide a lane assist system for a motor vehicle including a surround sensor device ~~(31)~~, which is mounted on the vehicle ~~(10)~~, for detecting the lane ~~(20)~~ of the vehicle and a warning device ~~(32)~~ to alert the driver in the event of the vehicle ~~(40)~~ threatening to depart the lane ~~(20)~~ which, with the smallest possible disturbance of the passengers, still enables the driver to initiate an intuitive steering response in a danger situation, it is ~~proposed~~provided to design and set up the warning device in such a way that a vibration, noticeable to the driver, is generated in the driver seat, to the effect that the vibration is noticeable on the side on which a lane departure threatens or actually takes place.

Figure 2